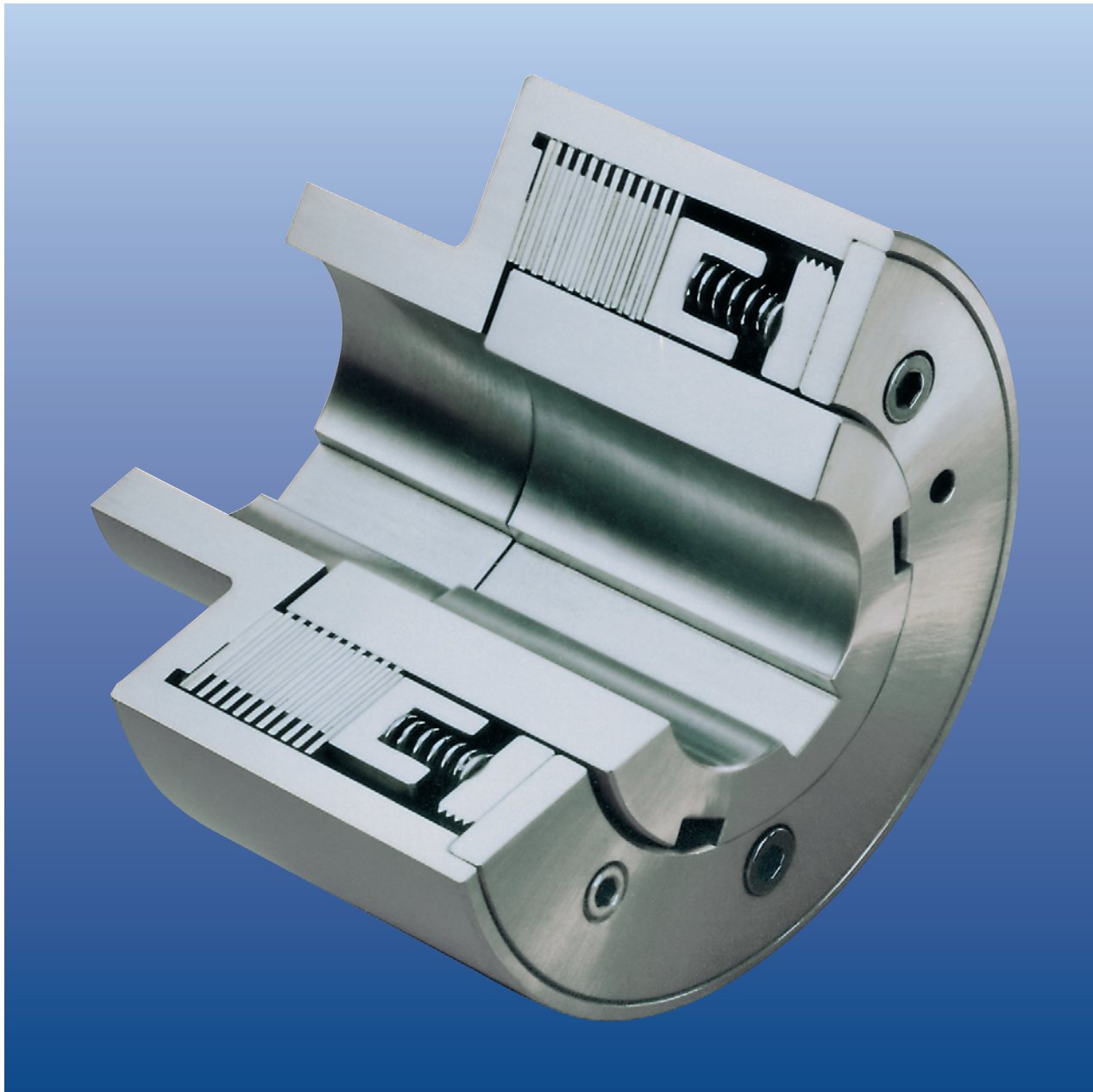


# ■ Safety, slipping and starting clutches



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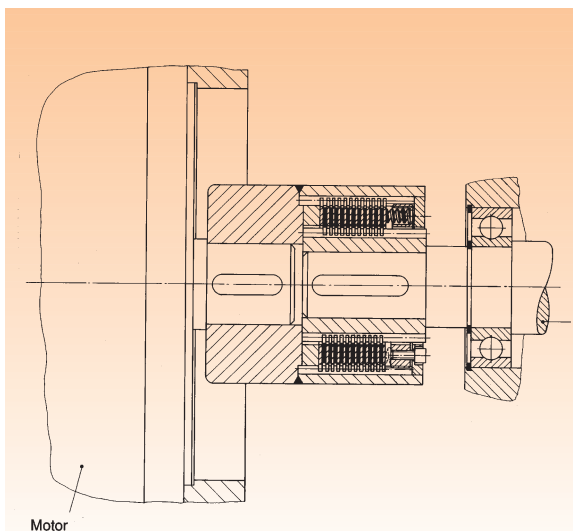


Ortlinghaus multiplate safety clutches are permanently engaged, this condition being maintained by spring pressure. They are able to transmit torque up to a particular, pre-set level, after which in the case of an overload in the transmission, they are designed, to slip for a limited period of time. They can thus be used to safeguard all types of transmission lines in machines and equipment from overloading and destruction. They have the task of smoothing out high torque peaks, at start ups, and during the operating of a line. This is done by the clutch plates slipping past each other for a short period of time when the desired maximum torque is reached. The torque at which a clutch starts to slip can be varied, within limits.

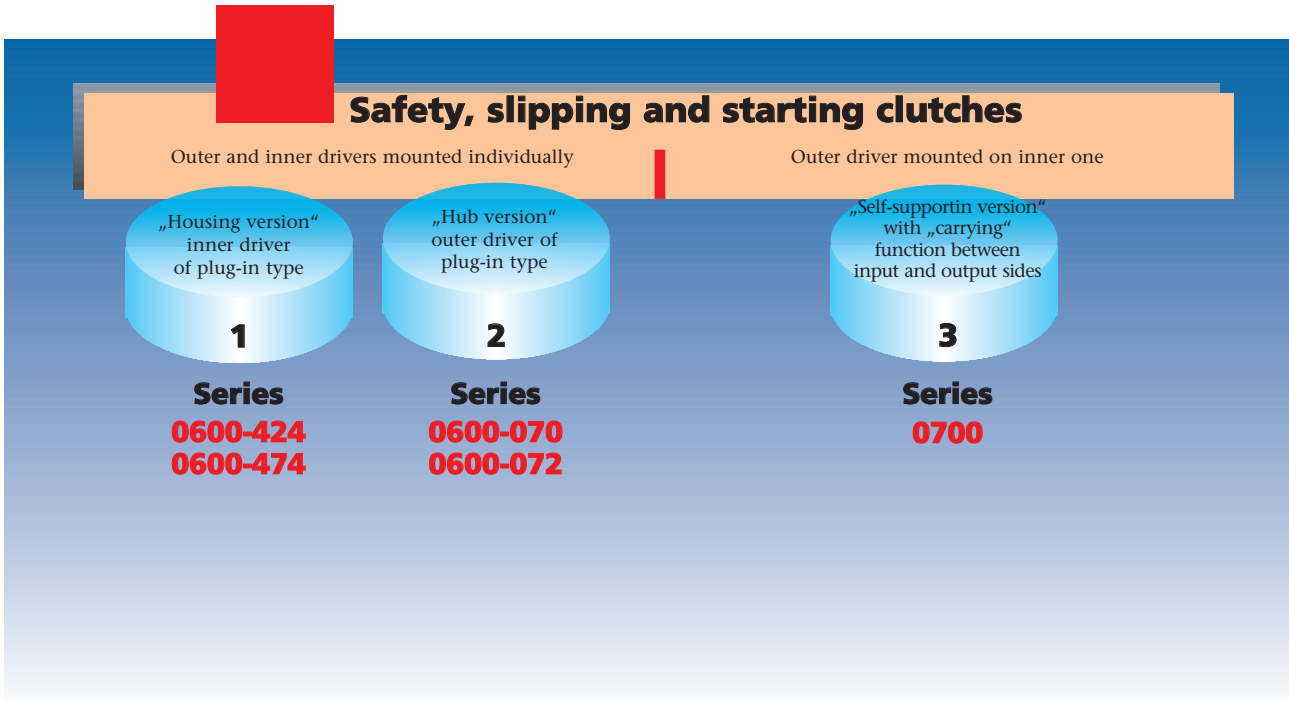
In this way these clutches safeguard gear wheels, shafts and other drive elements from damage and thus guarantee operational reliability for an extended period of time; in this way they also help to prevent the need for repairs.

It must be kept in mind that when the clutch is slipping, frictional heat is produced and released within the set of plates and that the permissible amount of heat is limited. This thermal loading must be kept within the required limit with the aid of a slip monitoring device, which would switch off the drive. This is necessary with fast running drives where the critical amount of heat is reached very rapidly when slipping commences.

## Fitting example



Ortlinghaus slipping clutch, series **0600-474**.  
Ortlinghaus slipping clutch fitted between a motor and a gearbox with separated shafts.



**Spring-engaged multiplate slipping clutches for dry-running or wet-running.**

**1/2/3 Series 0600 und 0700**

The principle of a spring loaded set of plates is the same with all sizes of clutch and all types.

However variations are possible in the following areas:

- The friction combination selected can be steel/organic lining for dry-running, and steel/sintered lining for both dry-running and for wet-running, e.g in closed gearboxes.
- Clutches are available with torques from 9 Nm to 90,000 Nm. The torque at which a clutch starts to slip can be selected or set on each clutch within the range from maximum torque down to

60% of the maximum torque. The torque at which each clutch starts to slip is set initially in our works but can subsequently be adjusted at any time. This facility enables plate wear to be taken into account and changed transmission conditions compensated for.

- The inner hub of the clutch is normally located on the machine shaft with the aid of a keyway. There are many different possible ways of connecting the outer housing of the clutch to the adjoining machine components.

No.	Series	Torque range Nm	Hub hole mm	Outer diam. mm
<b>1</b>	0600-424/-474	9 to 1600	10 to 80	70 to 210
<b>2</b>	0600-070/-072	90 to 90000	30 to 300	210 to 750
<b>3</b>	0700	9 to 1600	10 to 80	70 to 270

# Fax questionnaire for safety, slipping and starting clutches

Please complete in block capitals!

**Ortlinghaus** SINCE 1898

THE TECHNOLOGY OF CONTROLLED TORQUE

Sender:

Name, first name

Company

Department

Telephone (extension)

Fax

Recipient:

Ortlinghaus-Werke GmbH  
Kenkhauser Straße 125 · Postbox 14 40  
42907 Wermelskirchen · Germany  
Tel. +49 2196 85-0 · Fax +49 2196 855-444  
info@ortlinghaus.com · www.ortlinghaus.com

for the attention of (if known)

**Fax-No. +49 2196 855-444**

**Driving machine:**

Electric motor

Combustion engine

Hydraulic motor

Other:

**Transmission situation:**

\_\_\_\_\_  
\_\_\_\_\_

**Application:**

Starting clutch

Overload protection

**Fitting situation:**

Axis of rotation horizontal

vertical

exposed

in closed housing

**Shaft diameter:**

on input side  $d_1 =$  \_\_\_\_\_ mm

on output side  $d_2 =$  \_\_\_\_\_ mm

**Motor data:**

Output  $P =$  \_\_\_\_\_ kW

Speed  $n =$  \_\_\_\_\_  $\text{min}^{-1}$

**Clutch torque:**

$M_U =$  \_\_\_\_\_ Nm

**Slipping torque:**

$M_R =$  \_\_\_\_\_ Nm

**Slipping speed:**

$n_R =$  \_\_\_\_\_  $\text{min}^{-1}$

**Slipping time per  
slipping period:**

$t_R =$  \_\_\_\_\_ s

**Slipping frequency:**

$S_h =$  \_\_\_\_\_  $\text{h}^{-1}$

**Moments of inertia about the  
clutch shaft axis:**

input side  $J_A =$  \_\_\_\_\_  $\text{kgm}^2$

output side  $J_L =$  \_\_\_\_\_  $\text{kgm}^2$

maximum  $J_L$  occurring: = \_\_\_\_\_  $\text{kgm}^2$

**Further details:**

\_\_\_\_\_  
\_\_\_\_\_  
\_\_\_\_\_  
\_\_\_\_\_  
\_\_\_\_\_  
\_\_\_\_\_